

# Real Time Linux (PREEMPT\_RT)

Matthias Lüscher, 3. September 2018

*"Controlling a laser with Linux is crazy, but everyone in this room is crazy in his own way. So if you want to use Linux to control an industrial welding laser, I have no problem with your using PREEMPT\_RT."*

Linus Torvalds, Kernel Summit 2006

# Content

- Real time Linux **sample applications**
- **Enabling real time Linux** by using PREEMPT\_RT
- **Architectural considerations** when using PREEMPT\_RT

# Sample Applications

- **Example 1: NI Linux Real-Time**  
<http://www.ni.com/white-paper/14627/de/>  
<http://www.ni.com/pdf/product-flyers/compactrio-controller.pdf>
- **Example 2: Maybe the industrial welding laser Linus Torvalds was talking about (video)**
- **More Examples: Industrial Companies**  
Join the OSADL (<https://www.osadl.org>) and ask the members about their usage of PREEMPT\_RT

# Enabling Real Time Linux (Generic)

## Getting the sources:

```
wget https://www.kernel.org/pub/linux/kernel/v4.x/linux-4.4.12.tar.xz
wget https://www.kernel.org/pub/linux/kernel/projects/rt/4.4/patch-4.4.12-rt19.patch.xz
```

## Applying the PREEMPT\_RT patch set:

```
xz -cd linux-4.4.12.tar.xz | tar xvf -
cd linux-4.4.12
xzcat ../patch-4.4.12-rt19.patch.xz | patch -p1
```

## Configuring the kernel:

The only necessary configuration for real time Linux kernel is the choice of the “Fully Preemptible Kernel” preemption model (CONFIG\_PREEMPT\_RT\_FULL).

## Building the kernel:

Building the kernel and starting the kernel works similarly to a kernel without PREEMPT\_RT patch.

# Enabling Real Time Linux (Debian, amd64)

For Debian, there are **real time images available** for the amd64 architecture:

```
sudo apt install linux-image-rt-amd64
```

# Enabling Real Time Linux (Results)

## Without PREEMPT\_RT patch:

```
pi@raspberrypi:~$ uname -a
Linux raspberrypi 4.17.0-0.bpo.1-arm64 #1 SMP Debian 4.17.8-1~bpo9+1 (2018-07-23)
aarch64 GNU/Linux
pi@raspberrypi:~$ sudo cyclictst -p 99 -t5 -n -i250
# /dev/cpu_dma_latency set to 0us
policy: fifo: looadavg: 0.32 0.42 0.22 1/140 2387

T: 0 ( 1856) P:99 I:250 C:1736556 Min:      9 Act:      12 Avg:      14 Max:      4975
T: 1 ( 1857) P:99 I:750 C: 578996 Min:      9 Act:      14 Avg:      14 Max:      4315
T: 2 ( 1858) P:99 I:1250 C: 347406 Min:      9 Act:      14 Avg:      15 Max:      4318
T: 3 ( 1859) P:99 I:1750 C: 248151 Min:      9 Act:      13 Avg:      14 Max:      1195
T: 4 ( 1860) P:99 I:2250 C: 193006 Min:      9 Act:      12 Avg:      14 Max:      991
```

## With PREEMPT\_RT patch:

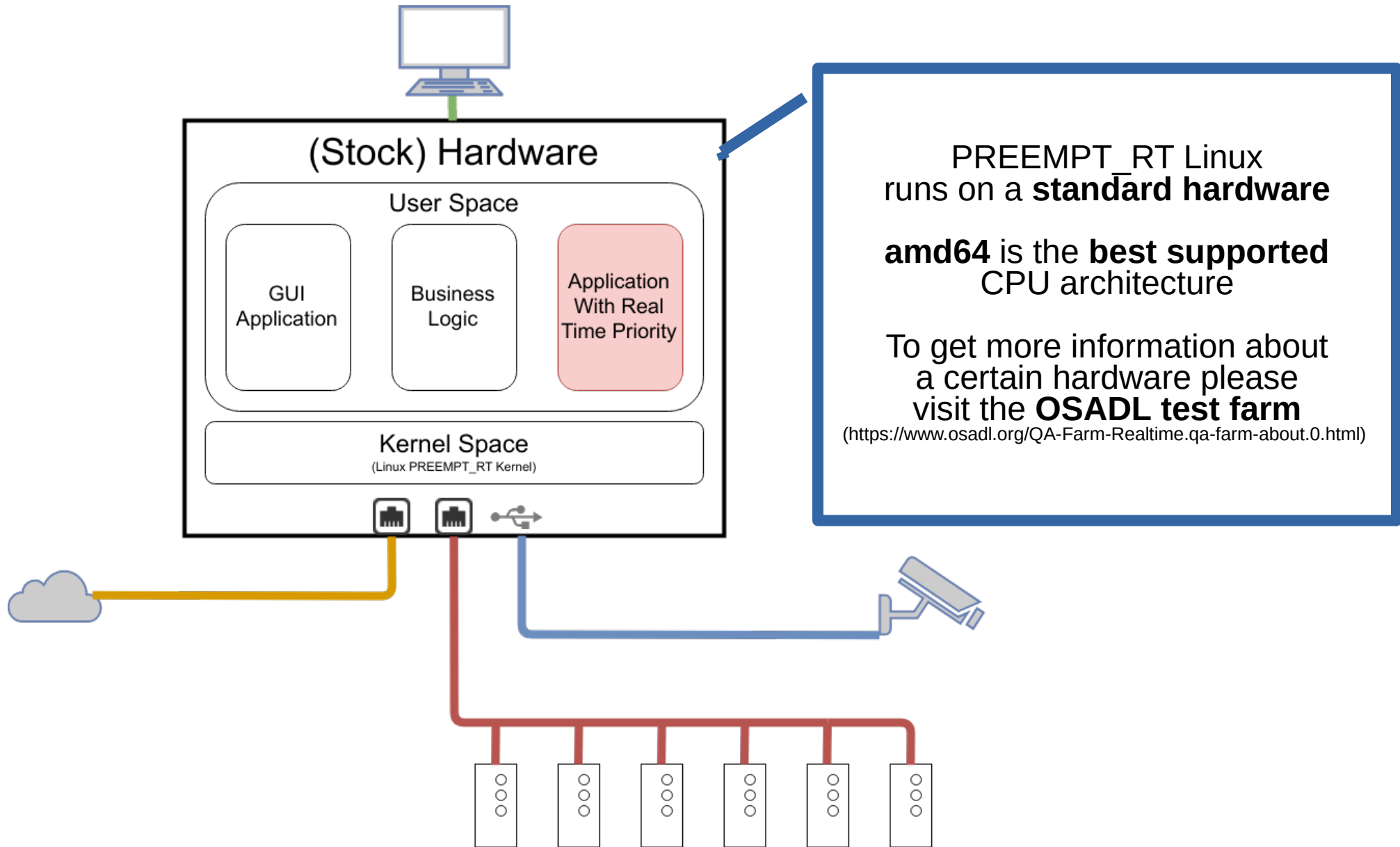
```
pi@raspberrypi:~$ uname -a
Linux raspberrypi 4.18.5-rt3-v8 #1 SMP PREEMPT RT Fri Aug 31 08:13:54 UTC 2018 aarch64
GNU/Linux
pi@raspberrypi:~$ sudo cyclictst -p99 -t5 -n -i250
# /dev/cpu_dma_latency set to 0us
policy: fifo: looadavg: 0.76 0.84 0.46 1/158 1526

T: 0 ( 1246) P:99 I:250 C: 995343 Min:     12 Act:     19 Avg:     23 Max:     152
T: 1 ( 1247) P:99 I:750 C: 331780 Min:     13 Act:     17 Avg:     19 Max:     94
T: 2 ( 1248) P:99 I:1250 C: 199068 Min:     14 Act:     21 Avg:     20 Max:    128
T: 3 ( 1249) P:99 I:1750 C: 142191 Min:     13 Act:     30 Avg:     29 Max:    151
T: 4 ( 1250) P:99 I:2250 C: 110593 Min:     14 Act:     19 Avg:     21 Max:    107
```

Test system: Raspberry Pi3, arm64

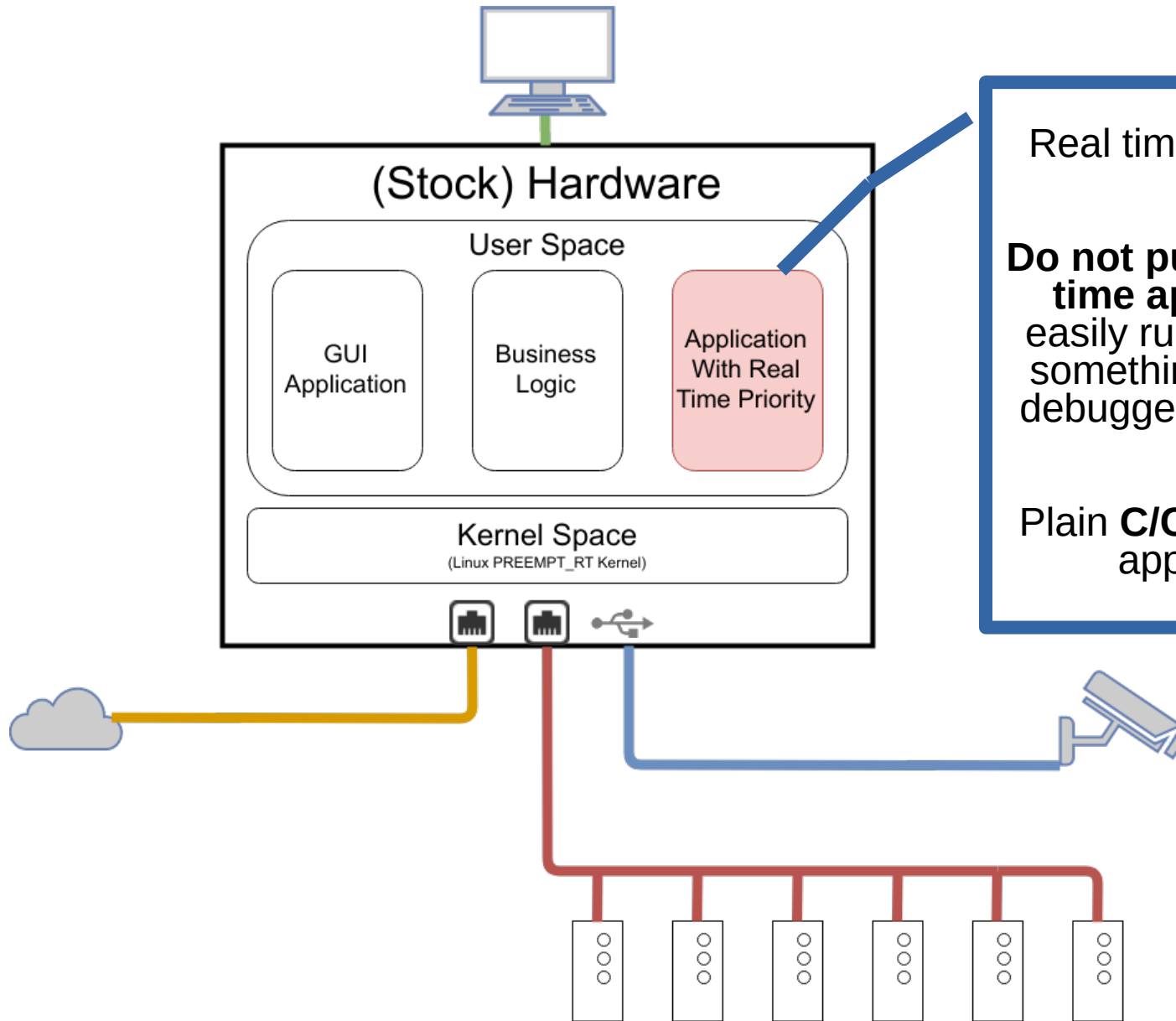
Setup: <https://www.get-edi.io/A-new-Approach-to-Operating-System-Image-Generation/>

# Architectural Considerations (Hardware)





# Architectural Considerations (Software)

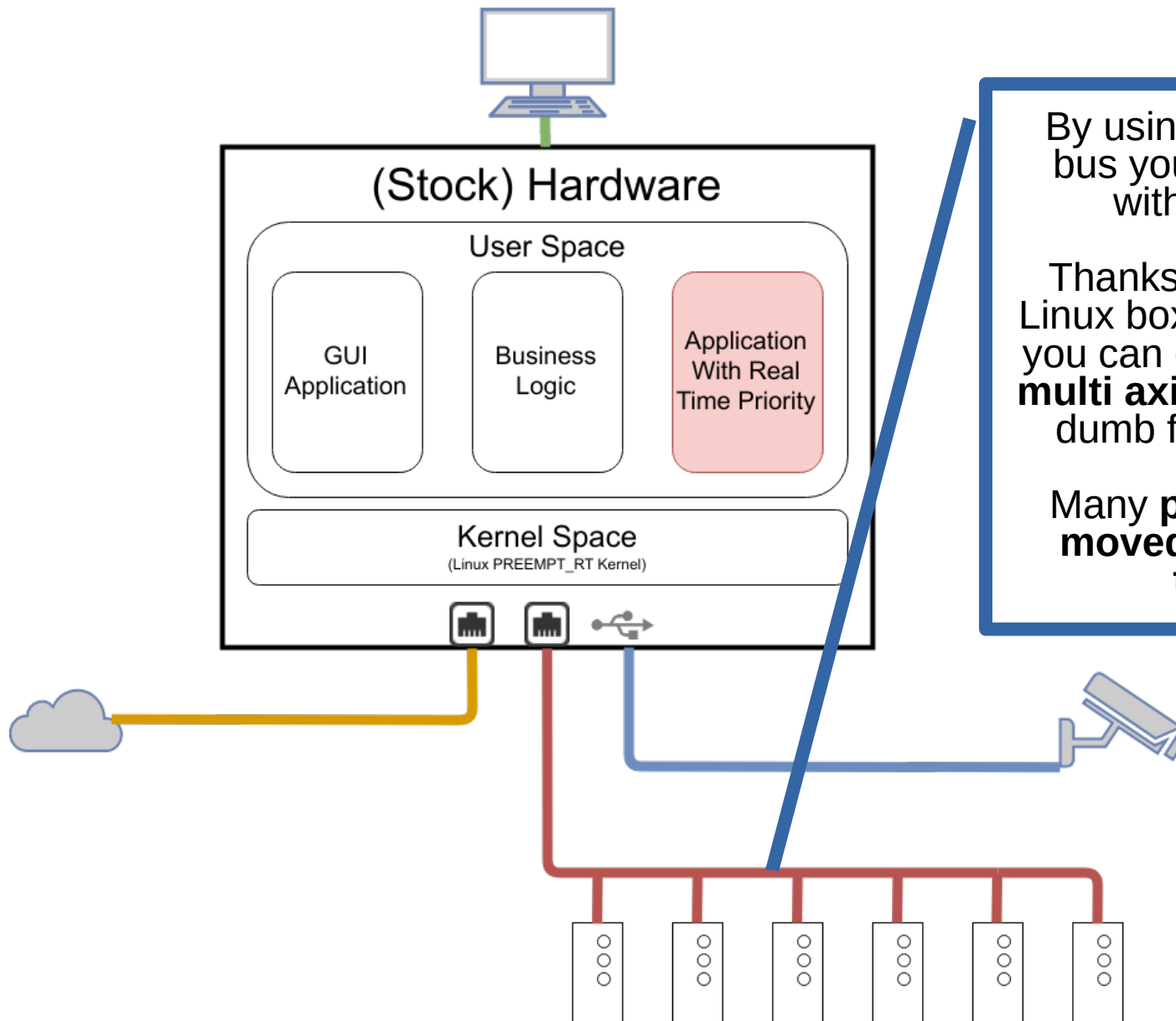


Real time application runs in **user space**

**Do not put everything into the real time application** since you can easily run into troubles when doing something wrong (and obviously a debugger would break the real time behavior)

Plain **C/C++** is suitable for real time application development

# Architectural Considerations (Fieldbus)



By using an Ethernet based field bus you can run **update cycles** with a frequency of **5kHz**

Thanks to the CPU power of the Linux box and its real time behavior you can centrally **control complex multi axis machines** with relatively dumb field bus controller nodes

Many **processing tasks** can be **moved** from the field bus node **to the Linux box**

# Conclusion

- PREEMPT\_RT patched Linux is **heavily used in industry**
- PREEMPT\_RT Linux is a **brilliant combination** of a **general purpose** operating system with a **real time operating system**
- PREEMPT\_RT patched Linux is in many cases a **suitable replacement for proprietary real time operating systems**
- CONFIG\_PREEMPT\_RT\_FULL is **not yet fully merged into mainline Linux**
- Please consider to (financially) **support the great team** of Linux developers that make PREEMPT\_RT available and further develop it